H24年度VBLプロジェクト研究の概要

Touch sensors for robotics

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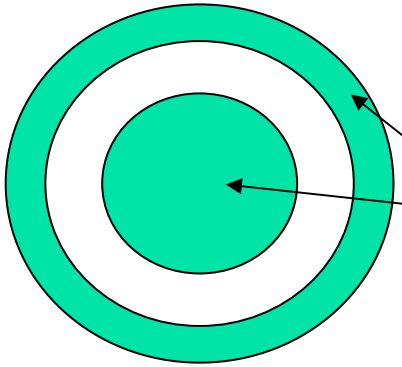
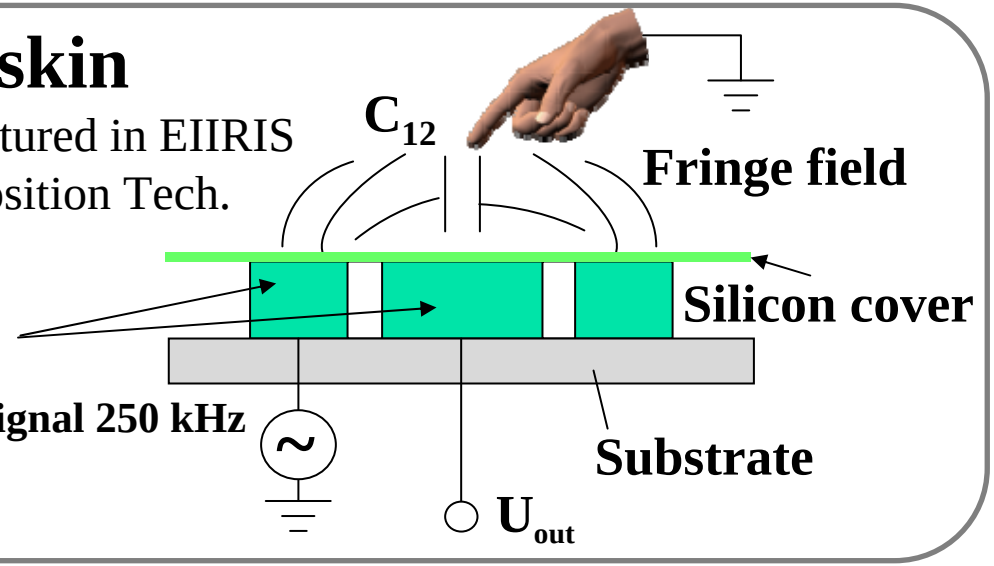
H23年度：研究目的と成果

Circular structure



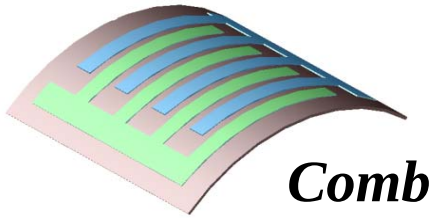
Robot skin

Graphen will be manufactured in EIIRIS by Chemical Vapor Deposition Tech.



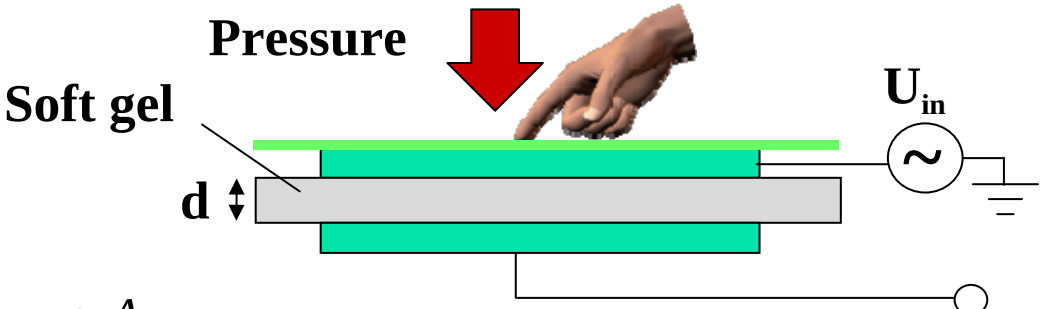
Capacitive graphene touch sensor

When the finger touches the sensor surface, the distance between the sheets decreases.



Comb structure

Plastic cover protect s the graphene from dirt and spillage.



$$C = \frac{Q}{V} = \frac{e_0 A}{d}$$

Parallel structure

H24年度計画

- Design the touch sensor based on graphene technology
- Manufacturing the touch sensor